### Exceptional numbers

Alberto Elduque

Universidad de Zaragoza

May 2009

Quaternions

- 2 Rotations in euclidean space

4 Octonions

Quaternions

- 2 Rotations in euclidean space

4 Octonions

$$\mathbb{C} = \{a + bi : a, b \in \mathbb{R}\} (\simeq \mathbb{R}^2)$$

$$\mathbb{C}=\{a+bi:a,b\in\mathbb{R}\}\,(\simeq\mathbb{R}^2)$$
  $|z_1z_2|=|z_1||z_2|$  (where  $|.|$  denotes the euclidean norm)

$$\mathbb{C}=\{a+bi:a,b\in\mathbb{R}\}\,(\simeq\mathbb{R}^2)$$
  $|z_1z_2|=|z_1||z_2|$  (where  $|.|$  denotes the euclidean norm)

Rotation of angle  $\alpha$  in  $\mathbb{R}^2 \leftrightarrow$  multiplication by  $e^{i\alpha} = \cos \alpha + i \sin \alpha$ .

$$\mathbb{C}=\{a+bi:a,b\in\mathbb{R}\}\,(\simeq\mathbb{R}^2)$$
  $|z_1z_2|=|z_1||z_2|$  (where  $|.|$  denotes the euclidean norm)

Rotation of angle  $\alpha$  in  $\mathbb{R}^2 \leftrightarrow$  multiplication by  $e^{i\alpha} = \cos \alpha + i \sin \alpha$ .

$$SO(2) \simeq \{z \in \mathbb{C} : |z| = 1\} \simeq S^1$$



Hamilton asked himself whether it is possible to define a product, similar to the product of complex numbers, but in dimension 3, which should respect the "law of the moduli":  $(|z_1z_2| = |z_1||z_2|)$ :

Hamilton asked himself whether it is possible to define a product, similar to the product of complex numbers, but in dimension 3, which should respect the "law of the moduli":  $(|z_1z_2| = |z_1||z_2|)$ :

$$(a + bi + cj)(a' + b'i + c'j) = ????$$
  
(assuming  $i^2 = -1 = j^2$ )

Hamilton asked himself whether it is possible to define a product, similar to the product of complex numbers, but in dimension 3, which should respect the "law of the moduli":  $(|z_1z_2| = |z_1||z_2|)$ :

$$(a + bi + cj)(a' + b'i + c'j) = ????$$
  
(assuming  $i^2 = -1 = j^2$ )

Problem:

ij?, ji?

Hamilton asked himself whether it is possible to define a product, similar to the product of complex numbers, but in dimension 3, which should respect the "law of the moduli":  $(|z_1z_2| = |z_1||z_2|)$ :

$$(a + bi + cj)(a' + b'i + c'j) = ????$$
  
(assuming  $i^2 = -1 = j^2$ )

Problem: ij?, ji?

After years of trying hard, he found a solution on October 16, 1843.

Letter of Sir W. R. Hamilton to his son Rev. Archibald H. Hamilton, dated August 5, 1865:

#### MY DEAR ARCHIBALD -

- (1) I had been wishing for an occasion of corresponding a little with you on QUATERNIONS: and such now presents itself, by your mentioning in your note of yesterday, received this morning, that you "have been reflecting on several points connected with them" (the quaternions), "particularly on the Multiplication of Vectors."
- (2) No more important, or indeed fundamental question, in the whole Theory of Quaternions, can be proposed than that which thus inquires What is such MULTIPLICATION? What are its Rules, its Objects, its Results? What Analogies exist between it and other Operations, which have received the same general Name? And finally, what is (if any) its Utility?

(3) If I may be allowed to speak of myself in connexion with the subject, I might do so in a way which would bring you in, by referring to an ante-quaternionic time, when you were a mere child, but had caught from me the conception of a Vector, as represented by a Triplet: and indeed I happen to be able to put the finger of memory upon the year and month -October, 1843 - when having recently returned from visits to Cork and Parsonstown, connected with a meeting of the British Association, the desire to discover the laws of the multiplication referred to regained with me a certain strength and earnestness, which had for years been dormant, but was then on the point of being gratified, and was occasionally talked of with you. Every morning in the early part of the above-cited month, on my coming down to breakfast, your (then) little brother William Edwin, and yourself, used to ask me, "Well, Papa, can you multiply triplets"? Whereto I was always obliged to reply, with a sad shake of the head: "No, I can only add and subtract them."

(4) But on the 16th day of the same month - which happened to be a Monday, and a Council day of the Royal Irish Academy - I was walking in to attend and preside, and your mother was walking with me, along the Royal Canal, to which she had perhaps driven; and although she talked with me now and then, yet an under-current of thought was going on in my mind, which gave at last a result, whereof it is not too much to say that I felt at once the importance. An electric circuit seemed to close; and a spark flashed forth, the herald (as I foresaw, immediately) of many long years to come of definitely directed thought and work, by myself if spared, and at all events on the part of others, if I should even be allowed to live long enough distinctly to communicate the discovery.

Nor could I resist the impulse -unphilosophical as it may have been- to cut with a knife on a stone of Brougham Bridge<sup>1</sup>, as we passed it, the fundamental formula with the symbols, i, j, k; namely,

$$i^2 = j^2 = k^2 = ijk = -1$$

which contains the Solution of the Problem, but of course, as an inscription, has long since mouldered away. A more durable notice remains, however, on the Council Books of the Academy for that day (October 16th, 1843), which records the fact, that I then asked for and obtained leave to read a Paper on Quaternions, at the First General Meeting of the session: which reading took place accordingly, on Monday the 13th of the November following.

With this quaternion of paragraphs I close this letter I.; but I hope to follow it up very shortly with another.

Your affectionate father, WILLIAM ROWAN HAMILTON.

<sup>&</sup>lt;sup>1</sup>The actual name of the bridge is Broome

Ш

$$\mathbb{H} = \mathbb{R}1 \oplus \mathbb{R}i \oplus \mathbb{R}j \oplus \mathbb{R}k,$$

$$i^2 = j^2 = k^2 = -1,$$

$$ij = -ji = k, \quad jk = -kj = i, \quad ki = -ik = j.$$

$$\mathbb{H} = \mathbb{R}1 \oplus \mathbb{R}i \oplus \mathbb{R}j \oplus \mathbb{R}k,$$

$$i^2 = j^2 = k^2 = -1,$$

$$ij = -ji = k, \quad jk = -kj = i, \quad ki = -ik = j.$$



Hamilton and his quaternions

# Some properties of $\mathbb{H}$

# Some properties of ${\mathbb H}$

• 
$$|q_1q_2| = |q_1||q_2| \ \forall q_1, q_2 \in \mathbb{H}$$
  
 $(|a+bi+cj+dk|^2 = a^2 + b^2 + c^2 + d^2)$ 

# Some properties of $\mathbb H$

- $|q_1q_2| = |q_1||q_2| \ \forall q_1, q_2 \in \mathbb{H}$  $(|a+bi+cj+dk|^2 = a^2 + b^2 + c^2 + d^2)$
- $\mathbb H$  is an associative division algebra (but not commutative). Thus  $S^3\simeq\{q\in\mathbb H:|q|=1\}$  is a Lie group. (And this immediately implies that  $S^3$  is parallelizable.)

# Some properties of ${\mathbb H}$

- $|q_1q_2| = |q_1||q_2| \ \forall q_1, q_2 \in \mathbb{H}$  $(|a+bi+cj+dk|^2 = a^2 + b^2 + c^2 + d^2)$
- $\mathbb H$  is an associative division algebra (but not commutative). Thus  $S^3\simeq\{q\in\mathbb H:|q|=1\}$  is a Lie group. (And this immediately implies that  $S^3$  is parallelizable.)
- $\mathbb{H}_0 = \mathbb{R}i \oplus \mathbb{R}j \oplus \mathbb{R}k \simeq \mathbb{R}^3$ ,  $\mathbb{H} = \mathbb{R} \oplus \mathbb{H}_0$ , and  $\forall u, v \in \mathbb{H}_0$ :

$$uv = -u \cdot v + u \times v$$

(where  $u \cdot v$  and  $u \times v$  denote the usual scalar and cross products)

# Some properties of $\ensuremath{\mathbb{H}}$

- $|q_1q_2| = |q_1||q_2| \ \forall q_1, q_2 \in \mathbb{H}$  $(|a+bi+cj+dk|^2 = a^2 + b^2 + c^2 + d^2)$
- $\mathbb H$  is an associative division algebra (but not commutative). Thus  $S^3\simeq\{q\in\mathbb H:|q|=1\}$  is a Lie group. (And this immediately implies that  $S^3$  is parallelizable.)
- $\mathbb{H}_0 = \mathbb{R}i \oplus \mathbb{R}j \oplus \mathbb{R}k \simeq \mathbb{R}^3$ ,  $\mathbb{H} = \mathbb{R} \oplus \mathbb{H}_0$ , and  $\forall u, v \in \mathbb{H}_0$ :

$$uv = -u \cdot v + u \times v$$

(where  $u \cdot v$  and  $u \times v$  denote the usual scalar and cross products)

• 
$$\forall q=a1+u\in\mathbb{H},\ q^2=(a^2-u\cdot u)+2au,$$
 so 
$$\boxed{q^2-(2a)q+|q|^2=0} \hspace{0.5cm} (\mathbb{H} \text{ is a quadratic algebra})$$

# Some properties of $\mathbb H$

- $|q_1q_2| = |q_1||q_2| \ \forall q_1, q_2 \in \mathbb{H}$  $(|a+bi+cj+dk|^2 = a^2 + b^2 + c^2 + d^2)$
- $\mathbb H$  is an associative division algebra (but not commutative). Thus  $S^3\simeq\{q\in\mathbb H:|q|=1\}$  is a Lie group. (And this immediately implies that  $S^3$  is parallelizable.)
- $\mathbb{H}_0 = \mathbb{R}i \oplus \mathbb{R}j \oplus \mathbb{R}k \simeq \mathbb{R}^3$ ,  $\mathbb{H} = \mathbb{R} \oplus \mathbb{H}_0$ , and  $\forall u, v \in \mathbb{H}_0$ :

$$uv = -u \cdot v + u \times v$$

(where  $u \cdot v$  and  $u \times v$  denote the usual scalar and cross products)

- $\forall q=a1+u\in\mathbb{H},\ q^2=(a^2-u\cdot u)+2au,$  so  $\boxed{q^2-(2a)q+|q|^2=0} \hspace{0.5cm} (\mathbb{H} \text{ is a quadratic algebra})$
- The map  $q=a+u\mapsto \bar{q}=a-u$  is an involution, with  $q+\bar{q}=2a$  and  $q\bar{q}=\bar{q}q=|q|^2$ .

Quaternions

2 Rotations in euclidean space

- 4 Octonions

$$q\in\mathbb{H},\ |q|=1\ \Rightarrow \exists lpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1$$
 such that  $q=(\coslpha)1+(\sinlpha)u$ 

$$q\in\mathbb{H},\;|q|=1\;\Rightarrow\existslpha\in[0,\pi],\;u\in\mathbb{H}_0,\;|u|=1$$
 such that  $q=(\coslpha)1+(\sinlpha)u$ 

Take  $v \in \mathbb{H}_0$  of norm 1 and orthogonal to u, so that  $\{u, v, u \times v\}$  is a positively oriented orthonormal basis of  $\mathbb{R}^3 = \mathbb{H}_0$ .

$$q\in\mathbb{H},\ |q|=1\ \Rightarrow \exists lpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1$$
 such that  $q=(\coslpha)1+(\sinlpha)u$ 

Take  $v \in \mathbb{H}_0$  of norm 1 and orthogonal to u, so that  $\{u, v, u \times v\}$  is a positively oriented orthonormal basis of  $\mathbb{R}^3 = \mathbb{H}_0$ .

Consider the linear map:

$$\varphi_q: \mathbb{H}_0 \longrightarrow \mathbb{H}_0,$$

$$x \mapsto qxq^{-1} = qx\bar{q}.$$

$$\varphi_q(u) = quq^{-1} = u$$
 (since  $uq = qu$ ),

$$\varphi_q(u) = quq^{-1} = u \qquad (\text{since } uq = qu),$$

$$\varphi_q(v) = ((\cos \alpha)1 + (\sin \alpha)u)v((\cos \alpha)1 - (\sin \alpha)u)$$

$$= ((\cos \alpha)v + (\sin \alpha)u \times v)((\cos \alpha)1 - (\sin \alpha)u)$$

$$= (\cos^2 \alpha)v + 2(\cos \alpha \sin \alpha)u \times v - (\sin^2 \alpha)(u \times v) \times u$$

$$= (\cos 2\alpha)v + (\sin 2\alpha)u \times v,$$

$$\varphi_q(u) = quq^{-1} = u \qquad (\operatorname{since} uq = qu),$$

$$\varphi_q(v) = ((\cos \alpha)1 + (\sin \alpha)u)v((\cos \alpha)1 - (\sin \alpha)u)$$

$$= ((\cos \alpha)v + (\sin \alpha)u \times v)((\cos \alpha)1 - (\sin \alpha)u)$$

$$= (\cos^2 \alpha)v + 2(\cos \alpha \sin \alpha)u \times v - (\sin^2 \alpha)(u \times v) \times u$$

$$= (\cos 2\alpha)v + (\sin 2\alpha)u \times v,$$

 $\varphi_{\alpha}(u \times v) = \dots = -(\sin 2\alpha)v + (\cos 2\alpha)u \times v.$ 

### Coordinate matrix $arphi_{m{q}}$

Therefore the coordinate matrix of  $\varphi_q$  relative to the basis  $\{u,v,u\times v\}$  is

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 2\alpha & -\sin 2\alpha \\ 0 & \sin 2\alpha & \cos 2\alpha \end{pmatrix},$$

### Coordinate matrix $\varphi_q$

Therefore the coordinate matrix of  $\varphi_q$  relative to the basis  $\{u,v,u\times v\}$  is

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 2\alpha & -\sin 2\alpha \\ 0 & \sin 2\alpha & \cos 2\alpha \end{pmatrix},$$

 $\varphi_a$  is the rotation of angle  $2\alpha$  relative to the axis  $\mathbb{R}^+u$ .

The map

$$arphi: \mathcal{S}^3 \simeq \{q \in \mathbb{H}: |q|=1\} \longrightarrow \mathcal{SO}(3), \ q \mapsto arphi_q$$

is a surjective homomorphism of (Lie) groups with  $\ker \varphi = \{\pm 1\}$ :

The map

$$arphi: \mathcal{S}^3 \simeq \{q \in \mathbb{H}: |q|=1\} \longrightarrow \mathcal{SO}(3), \ q \mapsto arphi_q$$

is a surjective homomorphism of (Lie) groups with  $\ker \varphi = \{\pm 1\}$ :

$$S^3/_{\{\pm 1\}} \simeq SO(3)$$

The map

$$arphi:S^3\simeq\{q\in\mathbb{H}:|q|=1\}\longrightarrow SO(3), \ q\mapsto arphi_q$$

is a surjective homomorphism of (Lie) groups with  $\ker \varphi = \{\pm 1\}$ :

$$S^3/_{\{\pm 1\}}\simeq SO(3)$$

 $(S^3)$  is the universal cover of SO(3)

Rotations in the euclidean space  $\begin{tabular}{ll} \longleftrightarrow & Conjugation in $\mathbb{H}_0$ by quaternions of norm 1 "modulo <math display="inline">\pm 1$ "

Rotations in the euclidean space  $\begin{tabular}{ll} \longleftrightarrow & Conjugation in $\mathbb{H}_0$ by quaternions of norm 1 "modulo <math display="inline">\pm 1$ "

It is quite easy to compose rotations in the euclidean space!

It is enough to multiply norm 1 quaternions!  $(\varphi_p \circ \varphi_q = \varphi_{pq})$ 

Rotations in the euclidean space  $\begin{tabular}{ll} \longleftrightarrow & Conjugation in $\mathbb{H}_0$ by quaternions of norm 1 "modulo <math display="inline">\pm 1$ "

It is quite easy to compose rotations in the euclidean space!

It is enough to multiply norm 1 quaternions!  $(\varphi_{\it p} \circ \varphi_{\it q} = \varphi_{\it pq})$ 

Now it is straightforward to deduce the formulae by Olinde Rodrigues (1840) for the composition of rotations.

•  $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .

- $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .
- $\forall q \in \mathbb{H}$ , The right multiplication by q is a  $\mathbb{C}$ -linear map. For  $q = z_1 + z_2 j$   $(z_1, z_2 \in \mathbb{C})$ , the (row) coordinate matrix is

$$\begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix}.$$

- $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .
- $\forall q \in \mathbb{H}$ , The right multiplication by q is a  $\mathbb{C}$ -linear map. For  $q = z_1 + z_2 j$   $(z_1, z_2 \in \mathbb{C})$ , the (row) coordinate matrix is

$$\begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix}.$$

• A one-to-one homomorphism of real algebras is thus obtained:  $\mathbb{H} \to \mathsf{Mat}_2(\mathbb{C}), \ q \mapsto R_q$ , which induces a (Lie) group isomorphism.

- $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .
- $\forall q \in \mathbb{H}$ , The right multiplication by q is a  $\mathbb{C}$ -linear map. For  $q = z_1 + z_2 j$   $(z_1, z_2 \in \mathbb{C})$ , the (row) coordinate matrix is

$$\begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix}.$$

• A one-to-one homomorphism of real algebras is thus obtained:  $\mathbb{H} \to \mathsf{Mat}_2(\mathbb{C}), \ q \mapsto R_q$ , which induces a (Lie) group isomorphism.

- $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .
- $\forall q \in \mathbb{H}$ , The right multiplication by q is a  $\mathbb{C}$ -linear map. For  $q = z_1 + z_2 j$   $(z_1, z_2 \in \mathbb{C})$ , the (row) coordinate matrix is

$$\begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix}.$$

• A one-to-one homomorphism of real algebras is thus obtained:  $\mathbb{H} \to \mathsf{Mat}_2(\mathbb{C}), \ q \mapsto R_q$ , which induces a (Lie) group isomorphism.

$$S^3 \simeq SU(2)$$

- $\mathbb{H} = \mathbb{C} \oplus \mathbb{C} j \simeq \mathbb{C}^2$  is a two dimensional vector space over  $\mathbb{C}$ .
- $\forall q \in \mathbb{H}$ , The right multiplication by q is a  $\mathbb{C}$ -linear map. For  $q = z_1 + z_2 j$   $(z_1, z_2 \in \mathbb{C})$ , the (row) coordinate matrix is

$$\begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix}.$$

• A one-to-one homomorphism of real algebras is thus obtained:  $\mathbb{H} \to \mathsf{Mat}_2(\mathbb{C}), \ q \mapsto R_q$ , which induces a (Lie) group isomorphism.

$$S^3 \simeq SU(2)$$

(The isomorphism  $SO(3) \simeq PSU(2)$  is deduced too.)

Quaternions

- 2 Rotations in euclidean space

4 Octonions

•  $\forall p \in \mathbb{H}$  with |p| = 1, the left and right multiplications by p:  $L_p$  and  $R_p$ , are isometries, thanks to the multiplicative property of the norm.

- $\forall p \in \mathbb{H}$  with |p| = 1, the left and right multiplications by p:  $L_p$  and  $R_p$ , are isometries, thanks to the multiplicative property of the norm.
- For  $p=(\cos\alpha)1+(\sin\alpha)u$ ,  $(\alpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1)$ , we have  $p^2-2(\cos\alpha)p+1=0$ , and hence the minimal polynomial of the multiplication by p is  $X\pm1$  if  $p=\mp1$ , or the irreducible polynomial  $X^2-2(\cos\alpha)X+1$  otherwise.

- $\forall p \in \mathbb{H}$  with |p| = 1, the left and right multiplications by p:  $L_p$  and  $R_p$ , are isometries, thanks to the multiplicative property of the norm.
- For  $p=(\cos\alpha)1+(\sin\alpha)u$ ,  $(\alpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1)$ , we have  $p^2-2(\cos\alpha)p+1=0$ , and hence the minimal polynomial of the multiplication by p is  $X\pm1$  if  $p=\mp1$ , or the irreducible polynomial  $X^2-2(\cos\alpha)X+1$  otherwise.
- Hence the characteristic polynomial of the multiplication by p is always

$$\left(X^2-2(\cos\alpha)X+1\right)^2$$

and, in particular, the determinant of the multiplication by p is 1.

- $\forall p \in \mathbb{H}$  with |p| = 1, the left and right multiplications by p:  $L_p$  and  $R_p$ , are isometries, thanks to the multiplicative property of the norm.
- For  $p=(\cos\alpha)1+(\sin\alpha)u$ ,  $(\alpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1)$ , we have  $p^2-2(\cos\alpha)p+1=0$ , and hence the minimal polynomial of the multiplication by p is  $X\pm1$  if  $p=\mp1$ , or the irreducible polynomial  $X^2-2(\cos\alpha)X+1$  otherwise.
- Hence the characteristic polynomial of the multiplication by p is always

$$\left(X^2-2(\cos\alpha)X+1\right)^2$$

and, in particular, the determinant of the multiplication by p is 1.

- $\forall p \in \mathbb{H}$  with |p| = 1, the left and right multiplications by p:  $L_p$  and  $R_p$ , are isometries, thanks to the multiplicative property of the norm.
- For  $p=(\cos\alpha)1+(\sin\alpha)u$ ,  $(\alpha\in[0,\pi],\ u\in\mathbb{H}_0,\ |u|=1)$ , we have  $p^2-2(\cos\alpha)p+1=0$ , and hence the minimal polynomial of the multiplication by p is  $X\pm1$  if  $p=\mp1$ , or the irreducible polynomial  $X^2-2(\cos\alpha)X+1$  otherwise.
- Hence the characteristic polynomial of the multiplication by p is always

$$\left(X^2 - 2(\cos\alpha)X + 1\right)^2$$

and, in particular, the determinant of the multiplication by p is 1.

The multiplications by norm 1 quaternions are rotations of  $\mathbb{H} \simeq \mathbb{R}^4$ .

ullet If  $\psi$  is a rotation of  $\mathbb{R}^4\simeq\mathbb{H}$ ,  $a=\psi(1)$  is a norm 1 element in  $\mathbb{H}$ , so

$$L_{\bar{a}} \circ \psi(1) = \bar{a}a = |a|^2 = 1,$$

and  $L_{\bar{a}} \circ \psi$  is actually a rotation of  $\mathbb{R}^3 \simeq \mathbb{H}_0$ .

ullet If  $\psi$  is a rotation of  $\mathbb{R}^4\simeq\mathbb{H}$ ,  $a=\psi(1)$  is a norm 1 element in  $\mathbb{H}$ , so

$$L_{\bar{a}} \circ \psi(1) = \bar{a}a = |a|^2 = 1,$$

and  $L_{\bar{a}} \circ \psi$  is actually a rotation of  $\mathbb{R}^3 \simeq \mathbb{H}_0$ .

ullet Therefore, there is a norm 1 element  $q\in\mathbb{H}$ , such that

$$\bar{a}\psi(x) = qxq^{-1}$$

for any  $x \in \mathbb{H}$ . that is,:

$$\psi(x) = (aq)xq^{-1} \quad \forall x \in \mathbb{H}.$$

The map

$$\Psi: S^3 \times S^3 \longrightarrow SO(4),$$
$$(p,q) \mapsto \psi_{p,q} \ (x \mapsto pxq^{-1})$$

is a surjective homomorphism of (Lie) groups with  $\ker \Psi = \{\pm (1,1)\}.$ 

The map

$$\Psi: S^3 \times S^3 \longrightarrow SO(4),$$
$$(p,q) \mapsto \psi_{p,q} \ (x \mapsto pxq^{-1})$$

is a surjective homomorphism of (Lie) groups with  $\ker \Psi = \{\pm (1,1)\}.$ 

$$S^3 \times S^3/_{\{\pm(1,1)\}} \simeq SO(4)$$

The map

$$\Psi: S^3 \times S^3 \longrightarrow SO(4),$$
$$(p,q) \mapsto \psi_{p,q} \ (x \mapsto pxq^{-1})$$

is a surjective homomorphism of (Lie) groups with  $\ker \Psi = \{\pm (1,1)\}.$ 

$$S^3 \times S^3/_{\{\pm(1,1)\}} \simeq SO(4)$$

(The isomorphism  $SO(3) \times SO(3) \simeq PSO(4)$  is deduced too.)

It is quite easy to compose rotations in the four dimensional euclidean space!

It is enough to multiply pairs of norm 1 quaternions!

$$(\psi_{p_1,q_1} \circ \psi_{p_2,q_2} = \psi_{p_1p_2,q_1q_2})$$

It is quite easy to compose rotations in the four dimensional euclidean space!

It is enough to multiply pairs of norm 1 quaternions!

$$(\psi_{p_1,q_1} \circ \psi_{p_2,q_2} = \psi_{p_1p_2,q_1q_2})$$

#### Exercise

What kind of rotation is  $\psi_{p,q}$  if  $p + \bar{p} = 2\cos\alpha$  and  $q + \bar{q} = 2\cos\beta$ ?

It is quite easy to compose rotations in the four dimensional euclidean space!

It is enough to multiply pairs of norm 1 quaternions!

$$(\psi_{p_1,q_1} \circ \psi_{p_2,q_2} = \psi_{p_1p_2,q_1q_2})$$

#### Exercise

What kind of rotation is  $\psi_{p,q}$  if  $p + \bar{p} = 2\cos\alpha$  and  $q + \bar{q} = 2\cos\beta$ ?

**Solution:** It is a "double rotation" of angles  $\alpha + \beta$  and  $\alpha - \beta$ .

Quaternions

- 2 Rotations in euclidean space
- $\bigcirc$  Rotations in  $\mathbb{R}^4$

4 Octonions

Quaternions are obtained by doubling the complex numbers:

$$\mathbb{H} = \mathbb{C} \oplus \mathbb{C}i$$
.

Quaternions are obtained by doubling the complex numbers:

$$\mathbb{H} = \mathbb{C} \oplus \mathbb{C}i$$
.

If another doubling is performed, there appear the octonions (Graves – Cayley):

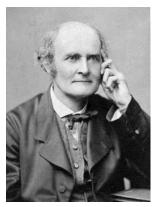
$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I$$
.

Quaternions are obtained by doubling the complex numbers:

$$\mathbb{H}=\mathbb{C}\oplus\mathbb{C}j.$$

If another doubling is performed, there appear the octonions (Graves – Cayley):

 $\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I$ .



Arthur Cayley

$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I = \mathbb{R}\langle 1, i, j, k, l, il, jl, kl \rangle$$

$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I = \mathbb{R}\langle 1, i, j, k, l, il, jl, kl \rangle$$

with multiplication

$$(p_1+p_2I)(q_1+q_2I)=(p_1q_1-\bar{q}_2p_2)+(q_2p_1+p_2\bar{q}_1)I$$

$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I = \mathbb{R}\langle 1, i, j, k, l, il, jl, kl \rangle$$

with multiplication

$$(p_1+p_2I)(q_1+q_2I)=(p_1q_1-\bar{q}_2p_2)+(q_2p_1+p_2\bar{q}_1)I$$

and norm:

$$|p_1 + p_2 I|^2 = |p_1|^2 + |p_2|^2$$

$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}I = \mathbb{R}\langle 1, i, j, k, l, il, jl, kl \rangle$$

with multiplication

$$(p_1+p_2I)(q_1+q_2I)=(p_1q_1-\bar{q}_2p_2)+(q_2p_1+p_2\bar{q}_1)I$$

and norm:

$$|p_1 + p_2 I|^2 = |p_1|^2 + |p_2|^2$$

These are the same formulae that allow to go from  $\mathbb C$  to  $\mathbb H!$ 

• |xy| = |x||y|,  $\forall x, y \in \mathbb{O}$ .

- |xy| = |x||y|,  $\forall x, y \in \mathbb{O}$ .
- O is a division algebra which is neither commutative nor associative!
   But it is alternative: every two elements generate an associative subalgebra.

**Theorem (Zorn 1933):** The only finite dimensional real alternative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{H}$  and  $\mathbb{O}$ .

The only finite dimensional real associative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$  and  $\mathbb{H}$  (Frobenius 1877).

- |xy| = |x||y|,  $\forall x, y \in \mathbb{O}$ .
- O is a division algebra which is neither commutative nor associative!
   But it is alternative: every two elements generate an associative subalgebra.
  - **Theorem (Zorn 1933):** The only finite dimensional real alternative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{H}$  and  $\mathbb{O}$ .
  - The only finite dimensional real associative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$  and  $\mathbb{H}$  (Frobenius 1877).
- $S^7 \simeq \{x \in \mathbb{O} : |x| = 1\}$  is not a group (the multiplication is not associative), but it is the most important example of a *Moufang loop*.

- |xy| = |x||y|,  $\forall x, y \in \mathbb{O}$ .
- ① is a division algebra which is neither commutative nor associative! But it is *alternative*: every two elements generate an associative subalgebra.

**Theorem (Zorn 1933):** The only finite dimensional real alternative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{H}$  and  $\mathbb{O}$ .

The only finite dimensional real associative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$  and  $\mathbb{H}$  (Frobenius 1877).

- $S^7 \simeq \{x \in \mathbb{O} : |x| = 1\}$  is not a group (the multiplication is not associative), but it is the most important example of a *Moufang loop*.
- $\mathbb{O}_0 = \mathbb{R}\langle i, j, k, l, il, jl, kl \rangle$ .  $\forall u, v \in \mathbb{O}_0$ :

$$uv = -u \cdot v + u \times v$$
.

(Cross product in  $\mathbb{R}^7$ !:  $(u \times v) \times v = (u \cdot v)v - (v \cdot v)u$ .)

- |xy| = |x||y|,  $\forall x, y \in \mathbb{O}$ .
- O is a division algebra which is neither commutative nor associative!
   But it is alternative: every two elements generate an associative subalgebra.

**Theorem (Zorn 1933):** The only finite dimensional real alternative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$ ,  $\mathbb{H}$  and  $\mathbb{O}$ .

The only finite dimensional real associative division algebras are  $\mathbb{R}$ ,  $\mathbb{C}$  and  $\mathbb{H}$  (Frobenius 1877).

- $S^7 \simeq \{x \in \mathbb{O} : |x| = 1\}$  is not a group (the multiplication is not associative), but it is the most important example of a *Moufang loop*.
- $\mathbb{O}_0 = \mathbb{R}\langle i, j, k, l, il, jl, kl \rangle$ .  $\forall u, v \in \mathbb{O}_0$ :

$$uv = -u \cdot v + u \times v$$
.

(Cross product in  $\mathbb{R}^7$ !:  $(u \times v) \times v = (u \cdot v)v - (v \cdot v)u$ .)

•  $\mathbb{O}$  is quadratic:  $\forall x = a1 + u \in \mathbb{O}, x^2 - 2ax + |x|^2 = 0$ .

• The groups  $Spin_7$  and  $Spin_8$  (universal covers of SO(7) and SO(8)) can be easily described in terms of the octonionic multiplication.

- The groups  $Spin_7$  and  $Spin_8$  (universal covers of SO(7) and SO(8)) can be easily described in terms of the octonionic multiplication.
- $\mathbb O$  division algebra  $\Rightarrow S^7$  is parallelizable.  $S^1$ ,  $S^3$  and  $S^7$  are the only parallelizable spheres (Milnor and Kervaire).

- The groups  $Spin_7$  and  $Spin_8$  (universal covers of SO(7) and SO(8)) can be easily described in terms of the octonionic multiplication.
- $\mathbb O$  division algebra  $\Rightarrow S^7$  is parallelizable.  $S^1$ ,  $S^3$  and  $S^7$  are the only parallelizable spheres (Milnor and Kervaire).
- $S^6 \simeq \{x \in \mathbb{O}_0 : |x| = 1\}$  has an almost complex structure, which is provided by the octonionic multiplication.  $S^2$  and  $S^6$  are the only spheres with this property (Adams).

- The groups  $Spin_7$  and  $Spin_8$  (universal covers of SO(7) and SO(8)) can be easily described in terms of the octonionic multiplication.
- $\mathbb O$  division algebra  $\Rightarrow S^7$  is parallelizable.  $S^1$ ,  $S^3$  and  $S^7$  are the only parallelizable spheres (Milnor and Kervaire).
- $S^6 \simeq \{x \in \mathbb{O}_0 : |x| = 1\}$  has an almost complex structure, which is provided by the octonionic multiplication.  $S^2$  and  $S^6$  are the only spheres with this property (Adams).
- Non-Desarguesian projective plane  $\mathbb{OP}^2$ .

- The groups  $Spin_7$  and  $Spin_8$  (universal covers of SO(7) and SO(8)) can be easily described in terms of the octonionic multiplication.
- $\mathbb O$  division algebra  $\Rightarrow S^7$  is parallelizable.  $S^1$ ,  $S^3$  and  $S^7$  are the only parallelizable spheres (Milnor and Kervaire).
- $S^6 \simeq \{x \in \mathbb{O}_0 : |x| = 1\}$  has an almost complex structure, which is provided by the octonionic multiplication.  $S^2$  and  $S^6$  are the only spheres with this property (Adams).
- Non-Desarguesian projective plane  $\mathbb{OP}^2$
- The only spheres which appear as homogeneous spaces of non classical groups are  $S^6 = \operatorname{Aut} \mathbb{O}/SU(3)$ ,  $S^7 = Spin_7/\operatorname{Aut} \mathbb{O}$  and  $S^{15} = Spin_9/Spin_7$ .

Finite dimensional simple Lie algebras over  ${\mathbb C}$ 

#### Finite dimensional simple Lie algebras over $\mathbb C$

• Four infinite families:  $A_n$ ,  $B_n$ ,  $C_n$ ,  $D_n$ ,

#### Finite dimensional simple Lie algebras over ${\mathbb C}$

- Four infinite families:  $A_n$ ,  $B_n$ ,  $C_n$ ,  $D_n$ ,
- Five exceptions:  $E_6$ ,  $E_7$ ,  $E_8$ ,  $F_4$ ,  $G_2$ .
  - 78, 133, 248, 52, 14.

#### Finite dimensional simple Lie algebras over ${\mathbb C}$

- Four infinite families:  $A_n$ ,  $B_n$ ,  $C_n$ ,  $D_n$ ,
- Five exceptions:  $E_6$ ,  $E_7$ ,  $E_8$ ,  $F_4$ ,  $G_2$ .
  - 78, 133, 248, 52, 14.

#### Finite dimensional simple Lie algebras over ${\mathbb C}$

- Four infinite families:  $A_n$ ,  $B_n$ ,  $C_n$ ,  $D_n$ ,
- Five exceptions:  $E_6$ ,  $E_7$ ,  $E_8$ ,  $F_4$ ,  $G_2$ . 78, 133, 248, 52, 14.

Each such algebra has a unique real compact form.



### $G_2$ and $F_4$

#### Cartan (1914)

$$\mathfrak{der}(\mathbb{O}) = \{ d \in \mathsf{End}(\mathbb{O}) : d(xy) = d(x)y + xd(y), \ \forall x, y \in \mathbb{O} \}$$

is the compact simple Lie algebra of type  $G_2$ .

### $G_2$ and $F_4$

#### Cartan (1914)

$$\mathfrak{der}(\mathbb{O}) = \{ d \in \mathsf{End}(\mathbb{O}) : d(xy) = d(x)y + xd(y), \ \forall x, y \in \mathbb{O} \}$$

is the compact simple Lie algebra of type  $G_2$ .

#### Chevalley-Schafer (1950)

 $\mathfrak{der}(\mathfrak{h}_3(\mathbb{O}))$  is the compact simple Lie algebra of type  $F_4$ .

# Freudenthal's Magic Square

# Freudenthal's Magic Square

	$\mathbb{R}$	$\mathbb{C}$	$\mathbb{H}$	0
$\mathbb{R}$	$A_1$	$A_2$	$C_3$	F <sub>4</sub>
$\mathbb{C}$	$A_2$	$A_2 \oplus A_2$	$A_5$	$E_6$
$\mathbb{H}$	C <sub>3</sub>	$A_5$	$D_6$	E <sub>7</sub>
$\mathbb{O}$	F <sub>4</sub>	$E_6$	E <sub>7</sub>	$E_8$

# Freudenthal's Magic Square

	$\mathbb{R}$	$\mathbb{C}$	$\mathbb{H}$	0
$\mathbb{R}$	$A_1$	$A_2$	$C_3$	F <sub>4</sub>
$\mathbb{C}$	$A_2$	$A_2 \oplus A_2$	$A_5$	$E_6$
$\mathbb{H}$	<i>C</i> <sub>3</sub>	$A_5$	$D_6$	E <sub>7</sub>
$\mathbb{O}$	F <sub>4</sub>	$E_6$	E <sub>7</sub>	<i>E</i> <sub>8</sub>



H. Freudenthal



# O is truly exceptional!

"The saying that God is the mathematician, so that, even with meager experimental support, a mathematically beautiful theory will ultimately have a greater chance of being correct, has been attributed to Dirac. Octonion algebra may surely be called a beautiful mathematical entity. Nevertheless, it has never been systematically utilized in physics in any fundamental fashion, although some attempts have been made toward this goal. However, it is still possible that non-associative algebras (other than Lie algebras) may play some essential future role in the ultimate theory, yet to be discovered." (S. Okubo 1995)

# O is truly exceptional!

"The saying that God is the mathematician, so that, even with meager experimental support, a mathematically beautiful theory will ultimately have a greater chance of being correct, has been attributed to Dirac. Octonion algebra may surely be called a beautiful mathematical entity. Nevertheless, it has never been systematically utilized in physics in any fundamental fashion, although some attempts have been made toward this goal. However, it is still possible that non-associative algebras (other than Lie algebras) may play some essential future role in the ultimate theory, yet to be discovered." (S. Okubo 1995)

# $\mathbb{O}$ is truly exceptional!

"The saying that God is the mathematician, so that, even with meager experimental support, a mathematically beautiful theory will ultimately have a greater chance of being correct, has been attributed to Dirac. Octonion algebra may surely be called a beautiful mathematical entity. Nevertheless, it has never been systematically utilized in physics in any fundamental fashion, although some attempts have been made toward this goal. However, it is still possible that non-associative algebras (other than Lie algebras) may play some essential future role in the ultimate theory, yet to be discovered." (S. Okubo 1995)

#### Thanks